

HESSI Recovery - Spacecraft Disassembly Procedure



Spacecraft Disassembly HSI_RCV_SC_Disassebly

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HESSI Recovery - Spacecraft Disassembly Procedure

1 Introduction

During environmental testing of HESSI, a vibration test anomaly caused severe damage to the spacecraft. The shaker delivered approximately 20G's, ten times the appropriate levels for the test. As a result, the spacecraft structure and the X-axis solar arrays were damaged. Thus, it is not known whether the HESSI spacecraft (S/C) is safe to lift in one piece.

The following procedure outlines the disassembly and removal of the spacecraft from the vibration table. The primary objectives of this are to [1] ensure nobody is harmed by having the spacecraft collapse on them; and [2] limit further damage to flight components during disassembly.

1.1 Signatures

Peter Harvey, HESSI Project Manager

Dr. David Pankow, HESSI Lead Mechanical Engineer

Ron Jackson, HESSI Quality Assurance

Frank Snow, HESSI Mission Manager

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1.2 Staffing Requirements:

The following people or their delegates are expected to be in place for the procedure.

| Item | Description | Name | Req'd/other |
|------|--|-----------------------------------|--------------------------|
| 1.1. | HESSI Spacecraft Disassembly Coordinator | Peter Harvey | Required |
| 1.2. | HESSI Spacecraft Lead Mechanical | Dave Pankow | |
| 1.3 | HESSI Imager Representative | Alex Zehnder and/or Peter Ming | Req'd for Imager Lift |
| 1.4 | HESSI Spectrometer Designer | Paul Turin | |
| 1.5. | HESSI Quality Assurance | Ron Jackson | Required |
| 1.6 | HESSI Bus Representative | John DiPalma or John Jordan | |
| 2. | JPL Representative / Instrumentation | Doug Perry | |
| 3 | FRB Representation | Rodney Phillips or Dan Worth | Required for S/C lift |

1.3 Disassembly Requirements

| Item | Requirement |
|------|--|
| 1 | All activities will be coordinated by the designated Disassembly Coordinator. |
| 2 | All activities will require FRB representative to be present. |
| 3 | As the blankets are removed, accelerometer locations must not be disturbed. |
| 4 | Photographs must be taken of all damage encountered. |
| 5 | If at any time, new structural damage is encountered, the Lead Mechanical engineer must assess the safety of continuing disassembly. |
| 6 | Redlines to this plan require notification to an FRB representative, and agreement by the Disassembly Coordinator and Mission QA. |

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2 FRB Requirements

The following measures are to be taken to insure the integrity of the accelerometers and cabling used in the control loop:

1. Move and tape the cables for the control and input monitor accelerometers closer to the test fixture without removing the piece of tape closest to the accelerometers.
2. Protect the control and input monitor accelerometers and the exposed length of associated cables using aluminum angle or padding and covered with black and yellow safety tape.
3. Secure the passageway between the control panel and the instrumentation patch panel.
4. Put out signs indicating that no one shall disconnect the cables to both the control panel and the instrumentation patch panel.
5. Verify the cable numbers to each accelerometer location before the accelerometer is removed.
6. Photograph each accelerometer location before the accelerometer is removed.
7. For each accelerometer, determine if it is attached and record for each location before removal.

| Accel | Location | Photo | Attached | Accel | Location | Photo | Attached |
|-------|----------|-------|----------|-------|----------|-------|----------|
| 1 | | | | 22 | | | |
| 2 | | | | 23 | | | |
| 3 | | | | 24 | | | |
| 4 | | | | 25 | | | |
| 5 | | | | 26 | | | |
| 6 | | | | 27 | | | |
| 7 | | | | 28 | | | |
| 8 | | | | 29 | | | |
| 9 | | | | 30 | | | |
| 10 | | | | 31 | | | |
| 11 | | | | 32 | | | |
| 12 | | | | 33 | | | |
| 13 | | | | 34 | | | |
| 14 | | | | 35 | | | |
| 15 | | | | 36 | | | |
| 16 | | | | 37 | | | |
| 17 | | | | 38 | | | |
| 18 | | | | 39 | | | |
| 19 | | | | 40 | | | |
| 20 | | | | 41 | | | |
| 21 | | | | 42 | | | |

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3 Pre-Disassembly

Prior to disassembly, JPL and FRB photographs will be taken to record the damage and possible help determine the cause of the anomaly. UCB, JPL and FRB representatives will inspect the spacecraft and the vibration test setup to their satisfaction.

At the current time, the spacecraft has been "safed" as follows:

- The Spectrometer Vacuum Pump is attached and operating;
- The Imager TMS test connector has been inserted;
- The PMT cover has been installed;
- The CSS covers (8) have been installed;
- The Battery Flight Plug has been removed;
- The spacecraft is unpowered.

Any other configuration comments may be noted by the Disassembly Coordinator and appended to the as-run of this procedure.

4 Disassembly Procedure

4.1 Attach Covers and Remove Harnessing

- Remove S/C to S/C GSE harness.
- Install connector covers
- Install RAS cover
- Install Fine Sun Sensor cover
- Remove Solar Array accelerometers
- Remove RAS Accelerometer

4.2 Remove Lower blankets

- Cut seam tape holding blankets on to allow removal without damage.
- Label each blanket with location per master S/C map and clean bag.

4.3 Remove Solar Arrays

- Remove -X panel in folded position.
 - Attach debris shield so nothing goes into the Spectrometer area.
 - Disconnect -X panel connectors (2).
 - Support the panel by hand using 2 people on each side of the panel.
 - Remove Lower Frangibolt.
 - Remove the Upper Frangibolt plate and Upper Frangibolt.
 - Unbolt from S/C
 - Lift away from S/C
 - Using 2 more people, unfold the array and lay flat in shipping container.
 - Remove debris shield
 - Bag Frangibolts and other bolts and mark as such.
 - Attach connector covers to S/C and to Array connectors.

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- Remove +X panel in folded position (same as -X)
- Deploy and remove +Y, -Y panels.

4.4 Remove Upper blankets

- Cut seam tape holding blankets on to allow removal without damage.
- Label each blanket with location per master S/C map and clean bag.

4.5 Photography and Damage Assessment

- Photograph any damage revealed by removal of solar arrays and blankets.
- Reassess structural integrity of the bus.

4.6 Remove Instrumentation

- Verify accelerometer attachment.
 - Identify any accelerometers that broke free during test.
 - Photograph accelerometers.
- Remove accelerometers, thermocouples, and TV heaters.
 - JPL personnel will remove accelerometers, TC's, and harnessing.
 - Cut extension wires to heaters, coil the remaining heater wire, and tape to heater.

4.7 Remove Imaging Components

4.7.1 Inspect and Secure Imager

- Inspect damage to mounting ring.
- Measure distance between attachment points.
- Add clamps to stabilize fractured ring if necessary.
- Add imager lift bars.
- Lower crane and lifting fixture over imager and attach to the 3 lifting bars.
- Support Imager weight using hydraset; i.e. lift with 47 kg (103 lbm).

4.7.2 Remove Harnessing

- Demate Transmit and Receive Coaxes from the Forward RF Antennae.
- Remove RF ties
- Remove RF coaxes from the Imager and secure to S/C deck.
- Demate 6 SAS Connectors
- Demate Lower Grid Tray Connector
- Demate Upper Grid Tray Connector
- Demate FSS Connector.

4.7.3 Remove Imager Tube and Trays

- Unbolt Imager from hard-points.
- Remove broken half of Imager Support Ring.
- Remove lower Imager blankets.
- Disconnect Imager harnesses.
- Lift Imager straight up utilizing crane and Hydraset.

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- Move Imager to transport Cradle.
- Install SAS lens covers.
- Remove FSS and Forward Antennas from Imager and store.
- Perform TMS in Vertical and Horizontal Positions.
- Secure and bag for transport.

4.8 Determine Bus structural integrity

- Inspect Bus for fractures, deformation, broken bolts, etc.
- Decide if Bus is safe to transport with boxes mounted.

4.9 Remove Unnecessary Masses

- If the structure is compromised, then
 - Remove Flight Battery
 - Remove Solid State Recorder
 - Remove SEM
 - Remove Transponder
 - Remove IDPU
 - Remove CPC
 - Remove IPC

4.10 Remove Vibration Fixture Bolts

- Remove "Guide" bolts (+X, -X, +Y, -Y) and record data in table 1.
- Insert alignment pins in the +X, -X, +Y and -Y positions.
- Remove the other 20 bolts and record data in table 1..

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Table 1.

| Bolt# | Removal Torque(in lb) | How Loose (# turns) |
|-------|-----------------------|---------------------|
| +X0 | | |
| +X1 | | |
| +X2 | | |
| +X3 | | |
| +X4 | | |
| +X5 | | |
| +X6 | | |
| +X7 | | |
| -X0 | | |
| -X1 | | |
| -X2 | | |
| -X3 | | |
| -X4 | | |
| -X5 | | |
| -X6 | | |
| -X7 | | |
| +Y0 | | |
| +Y1 | | |
| +Y2 | | |
| +Y3 | | |
| +Y4 | | |
| +Y5 | | |
| +Y6 | | |
| +Y7 | | |
| -Y0 | | |
| -Y1 | | |
| -Y2 | | |
| -Y3 | | |
| -Y4 | | |
| -Y5 | | |
| -Y6 | | |
| -Y7 | | |

X0 is TDC and X1 is clockwise looking from the top.

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4.11 Lift

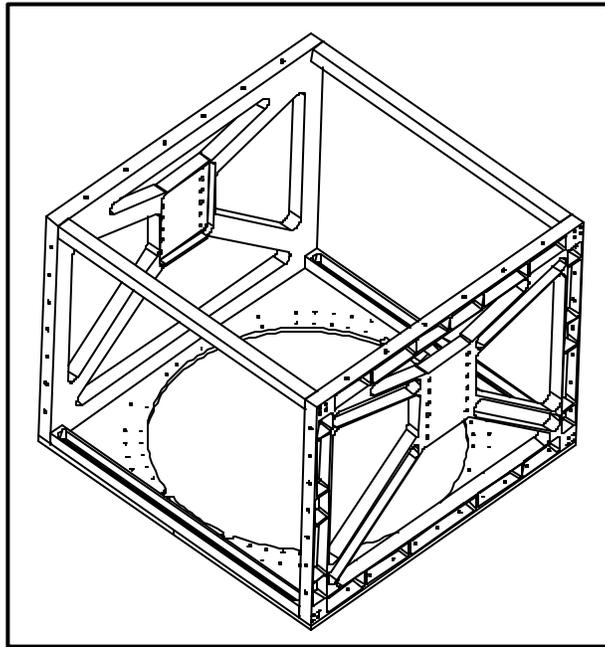
- Detach Spectrometer Pump.
- Lift Spectrometer Pump off vibration table and remount on Pump Cart Lift
- Install S/C lifting fixture to HESSI and attach to base ring.
- Lift S/C off vibration table vertically watching the 4 alignment pins.
- Move to S/C Dolly and secure.
- Remove lifting fixture
- Bolt down the force transducers with new bolts of appropriate length.

4.12 Safe Spacecraft

- Torque bolts holding S/C to dolly.
- Attach Spectrometer Pump.

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Appendix A.



HESSI SAI Lifting Fixture

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Table 2. Accelerometer List

| Description | X axis TEST | Y axis TEST | Z axis TEST | X axis Ch.I.D. | Y axis Ch.I.D. | Z axis Ch.I.D. |
|----------------------------|----------------|----------------|----------------|-------------------|-------------------|-------------------|
| *Spacecraft Base Ring 1 | 1(X,Y,Z) | 1(X,Y,Z) | 1(X,Y,Z) | 1,2,3 | 1,2,3 | 1,2,3 |
| *Spacecraft Base Ring 2 | 2X | 2Y | 2Z | 4 | 4 | 4 |
| *Spacecraft Base Ring 3 | 3X | 3Y | 3 | 5 | 5 | 5 |
| *Cryostat Inboard Attach 1 | 4(X,Y,Z) | 4(X,Y,Z) | 4(X,Y,Z) | 6,7,8 | 6,7,8 | 6,7,8 |
| *Cryostat Inboard Attach 2 | 5X | 5Y | 5Z | 9 | 9 | 9 |
| *Cryostat Inboard Attach 3 | 6X | 6Y | 6Z | 10 | 10 | 10 |
| *Imager Mount 1 | 7(X,Y,Z) | 7(X,Y,Z) | 7(X,Y,Z) | 11,12,13 | 11,12,13 | 11,12,13 |
| *Imager Mount 2 | 8X | 8Y | 8Z | 14 | 14 | 14 |
| *Imager Mount 3 | 9X | 9Y | 9Z | 15 | 15 | 15 |
| *Imager Top Ring | 10(X,Y) | 10(X,Y) | 10(X,Y) | 16,17 | 16,17 | 16,17 |
| *Imager Bottom Ring | 11(X,Y) | 11(X,Y) | 11(X,Y) | 18,19 | 18,19 | 18,19 |
| *Fine Sun Sensor | 12(X,Y,Z) | 12(X,Y,Z) | 12(X,Y,Z) | 20,21,22 | 20,21,22 | 20,21,22 |
| *Magnetometer | 13(X,Y,Z) | 13(X,Y,Z) | 13(X,Y,Z) | 23,24,25 | 23,24,25 | 23,24,25 |
| *#Deck, Box Foot Quad1 | 14(X,Y,Z) | 14(X,Y,Z) | 14(X,Y,Z) | 26,27,28 | 26,27,28 | 26,27,28 |
| Deck, Box Foot Quad 2 | 15Z | 15Z | 15Z | 29 | 29 | 29 |
| Deck, Box Foot Quad 3 | 16Z | 16Z | 16Z | 30 | 30 | 30 |
| Deck, Box Foot Quad 4 | 17Z | 17Z | 17Z | 31 | 31 | 31 |
| SSR, Inboard (neg R) | 18R | 18R | 18R | 32 | 32 | 32 |
| SEM, Outboard (pos R) | 19R | 19R | 19R | 33 | 33 | 33 |
| Particle Detector | 20Y | 20Y | 20Y | 34 | 34 | 34 |
| SA Wing X Upper TiNi | 21X | 21X | 21(X,Z) | 35 | 35 | 35,36 |
| SA Wing X Lower TiNi | 22X | 22X | 22(X,Z) | 37 | 37 | 37,38 |
| SA Wing X Lower Rt. Side | 23X | 23X | 23X | 39 | 39 | 39 |
| SA Wing X Mid. Rt. Side | 24X | 24X | 24X | 40 | 40 | 40 |
| SA Wing Y Upper TiNi | 25Y | 25Y | 25Y | 41 | 41 | 41 |
| SA Wing Y Lower TiNi | 26Y | 26Y | 26Y | 42 | 42 | 42 |
| SA Wing Y Lower Rt. Side | 27Y | 27Y | | 36 | 36 | |
| SA Wing Y Mid. Rt. Side | 28Y | 28Y | | 38 | 38 | |

- Notes:
- 1) The Asterisk indicates a tri-axial accelerometer
 - 2) Use low mass accelerometers
 - 3) Place accelerometer as close as possible to ...
 - 4) Place accelerometer on ...
 - 5) The “#” denotes location between SSR and IPC

4.12.1.1.1 Comments & Explanations

Columns 2,3,4 Identify the test axis & measuring locations. i.e. (X axis, 1X) means X direction during X test

Columns 5,6,7 are meant to represent data channels

Locations 1,2& 3 are intended to represent Vertical Planes that are indexed to the three Imager Hard Points